Title: Regularization Techniques Based on the Least Squares Method

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Abstract: In this thesis we consider a linear inverse problem $Ax \approx b$, where A is a linear operator with smoothing property and b represents an observation vector polluted by unknown noise. It was shown in [Hnětynková, Plešinger, Strakoš, 2009] that high-frequency noise reveals during the Golub-Kahan iterative bidiagonalization in the left bidiagonalization vectors. We propose a method that identifies the iteration with maximal noise revealing and reduces a portion of high-frequency noise in the data by subtracting the corresponding (properly scaled) left bidiagonalization vector from b. This method is tested for different types of noise. Further, Hnětynková, Plešinger, and Strakoš provided an estimator of the noise level in the data. We propose a modification of this estimator based on the knowledge of the point of noise revealing.

Keywords: ill-posed problems, regularization, Golub-Kahan iterative bidiagonalization, noise revealing, noise estimate, denoising